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**DRIVING POINT IMPEDANCE FOR A
LINEAR ARRAY OF HALF-WIDTH
LEAKY-WAVE ANTENNA (PREPRINT)**



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Driving Point Impedance for a Linear Array of Half-width Leaky-wave Antennas

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Abstract: Printed leaky-wave antennas offer the potential for a low-profile, wide-bandwidth antenna element that can be arrayed if desired. Microstrip leaky-wave antennas rely on the suppression of the familiar EH_0 mode and the propagation of the radiating EH_1 mode. It is well-known that above a critical frequency, this leaky-wave will propagate with little attenuation and that the phase difference between the two radiating edges of the microstrip leads to radiation. The driving point impedance for a given leaky-wave antenna

Keywords: Leaky-wave Antenna; Linear Array; Impedance

Introduction

Microstrip leaky-wave antennas offer the potential for a low-profile antenna with greater bandwidth than microstrip patch antennas. This is principally due to the fact that the radiation mechanism is attributed to a traveling-wave as compared to the standing-wave that is responsible for radiation by a microstrip patch antenna. The fundamental mode of a microstrip line, the so-called EH_0 mode, is not a radiating mode (hence the popularity of microstrip transmission lines). The electric and magnetic fields for this mode are shown in Figure 1.

Higher-order modes must be preferentially excited to realize a radiating traveling wave structure. The first higher-order mode, the EH_1 mode, is one such radiating mode. This mode (shown in Figure 2) exhibits electric field odd symmetry about the axial centerline of the antenna as compared to the even symmetry of the EH_0 mode.

A common method for estimating the radiation bandwidth of an EH_1 -mode antenna is based on a waveguide model [1-3]. The bandwidth of such an antenna is determined by the cut-off frequency for the EH_1 mode and the frequency where the phase constant equals k_0 (e.g. above this frequency, the bound mode propagates rather than the leaky-wave). This frequency range is given by

$$f_c = \frac{15}{w_{\text{eff}} \sqrt{\epsilon_r}} < f < \frac{f_c \sqrt{\epsilon_r}}{\sqrt{\epsilon_r - 1}} = \frac{15}{w_{\text{eff}} \sqrt{\epsilon_r - 1}} \quad (1)$$

where the zero-thickness effective width of the microstrip (in cm) is given by Wheeler [4-6]

$$w_{\text{eff}} = h \left\{ \frac{w}{h} + \frac{2}{\pi} \ln \left[2\pi e \left(\frac{w}{2h} + 0.92 \right) \right] \right\} \quad (2)$$

Operation of the microstrip in the range of frequencies specified by (1) will allow the propagation of the EH_1 leaky-wave mode; however, the fundamental EH_0 will also propagate and depending on the feeding

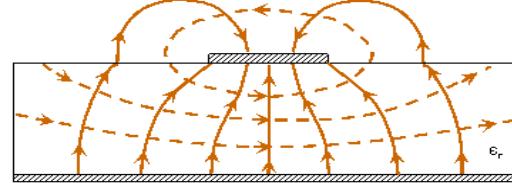


Figure 1. Field diagram for the EH_0 mode (E-field = solid, H-field = dashed).

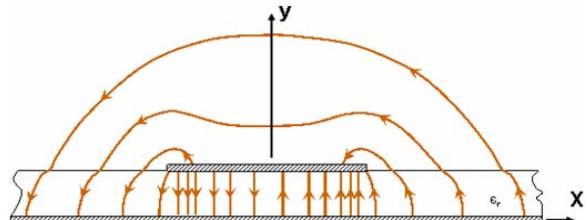


Figure 2. Field diagram for the EH_1 mode (E-field = solid, H-field = dashed).

structure, this fundamental mode may dominate. One significant challenge in realizing a printed leaky-wave antenna is the suppression of the fundamental mode in preference to the desired EH_1 mode. Various means of preferentially exciting the EH_1 mode have been investigated (see for example [3] and the references contained within that manuscript). Another means of preferentially exciting the EH_1 mode is to suppress the EH_0 mode. This was accomplished using small slots in the microstrip structure near the feed region by Mentzel [7] and an asymmetric microstrip feed (including a quarter wave transformer to improve the match to a 50Ω port). An alternative method, utilizing a physical grounding structure along the length of the antenna, has recently been investigated by the Air Force Research Laboratory [8]. The major advantage of such an antenna is the reduced width as compared to other leaky-wave microstrip antennas and the relatively simple feed structure. Recently, the FD-TD method was used to study this antenna [9] in addition to experiments. An alternative method is the finite element method that has the advantage of being able to model more complex geometrical aperture arrangements.

Finite Element-Boundary Integral Model of the Half-width Antenna

The FE-BI method has been extensively reported upon in the literature and is described in at least three popular text books on finite element methods for high frequency electromagnetics [10-12]. The FE-BI equations for a total electric field formulation may be written as

$$\int_V [\nabla \times \mathbf{W}_i \cdot \bar{\bar{\mu}}_r^{-1} \cdot \nabla \times \mathbf{W}_j] dV - k_0^2 \int_V [\mathbf{W}_i \cdot \bar{\bar{\epsilon}}_r \cdot \mathbf{W}_j] dV + jk_0 \int_{S_R} \left[\frac{(\hat{n}_R \times \mathbf{W}_i) \cdot (\hat{n}_R \times \mathbf{W}_j)}{R_e} \right] dS \\ - k_0^2 \int_{S_a} \int_{S_a} [\mathbf{W}_i \cdot \hat{z} \times \bar{\bar{G}}_{e2} \times \hat{z} \cdot \mathbf{W}_j] dS' dS = f_i^{\text{int}} + f_i^{\text{ext}} \quad (4)$$

where the first term is associated with the curl of the basis function (the magnetic field), the second term is associated with the basis function itself (the electric field), the third term is necessary to account for an resistive transition conditions if present, and the last term on the left-hand side is the boundary integral term (involving a second kind electric field dyadic Green's function). As shown, the material parameters are represented as tensors $(\bar{\bar{\epsilon}}_r, \bar{\bar{\mu}}_r)$ while the basis and test functions are represented by (\mathbf{W}_j) and (\mathbf{W}_i) , respectively. For this work, brick elements are used along with a half-space dyadic Green's function

$$\bar{\bar{G}}_{e2}(x, y | x', y') = \left[\bar{\bar{I}} + \frac{\nabla \nabla}{k_0^2} \right] \frac{e^{+jkR}}{2\pi R} \quad (5)$$

where **Error! Objects cannot be created from editing field codes.** and $R = \sqrt{(x - x')^2 + (y - y')^2 + (z - z')^2}$.

Candidate Half-width Leaky-wave Antenna

As an example, consider a leaky-wave antenna printed on Duroid 5870 (31 mils thick, $\epsilon_r = 2.33$, $\tan\delta = 0.0005$). The full-width strip width is 15 mm while the half-width strip width is 7.5 mm. The strip is 190 mm long and terminated with a lumped 50Ω load placed midway between the shorted edge and the free edge of the antenna. This load placement was determined, using TRM and confirmed using numerical techniques, as suitable for wide bandwidth termination of the antenna [14].

The half-width antenna utilizes a physical electric conducting wall to suppress the fundamental mode. This is accomplished in the finite element model with an infinitesimally thin perfect conducting wall while in the actual antenna constructed in the RASCAL facility at AFRL, the wall is formed with closely spaced periodic conducting pins. The feed is a probe feed placed half-way along the width of the half-width antenna (consistent with the placement of the co-planar microstrip feeds in [13]) and slightly inset. According to (1), the leaky-wave region of the antennas is given by $6.55 \text{ GHz} \leq f \leq 8.67 \text{ GHz}$. Below this range of frequency, the EH_1 mode is in cut-off while above that range, the bound mode is dominant. In [9], the data generated from both the FDTD and transverse resonance models indicate that the

attenuation of the propagating wave is quite small in the leaky-wave band and hence, a relatively short antenna (as is the one in this work) will have a significant backward traveling leaky-wave without a suitable termination.

Results for a Linear Array

For this study, the driving point impedance is computed for a single terminated element, three terminated elements, and five terminated elements. The apertures for these are shown in Figure 3. In this, the substrate is represented by blue, the microstrip structure by red, the shorting wall by white, the feed by a black dot, and the load by a green dot. As can be seen, the physical aperture dimensions were kept constant and the antenna was centered in the x-y plane.

To establish convergence of the geometrical/electrical representation of the antenna, the voltage standing wave ratio (VSWR) assuming a 50 Ohm port and a 50 Ohm termination impedance were calculated. The mesh density along the length was set at 0.125 cm while the density along the width of a single antenna (See Figure 3) was 0.25 cm, 0.125 cm, and 0.0625 cm. Since the antenna is assumed to be reasonably well-matched if meshed sufficiently, the longitudinal field variation is expected to be fairly small (e.g. little standing wave). Assuming a quasi-TEM wavelength, the longitudinal sample rate is approximately $\lambda_g / 20$. The lateral field variation is

expected to be one quarter of a sine function (see [3,14] for example), a higher sample rate may be necessary. Figure 4 illustrates the comparison showing that a lateral sample rate of $\lambda_g / 40$ is sufficient for understanding the local behavior of these antennas.

The input impedance is now compared for the three cases illustrated in Figure 3. It is expected that the input impedance will be impacted by the presence of both driven and passive near-by antennas due to the reasonably strong coupling between elements attributed to the leaky-wave itself. The results are shown in Figure 5 where the impedance of the center element for a 1x1 and a 5x1 array are shown in real and complex form from 5-9 GHz. As can be seen, both the resistance and the reactance exhibit variation due to the presence of driven near-by elements. Further examples involving the effect of passive elements will be shown at the meeting.

Conclusions

In this paper, the hybrid finite element-boundary integral method was used to investigate the properties of a leaky-wave antenna. The antenna under study was the half-width antenna recently introduced by Radcliffe *et al.* [8]. In this, a physical structure (realized via periodic shorting pins) is used to suppress the fundamental – even – mode. Probe feeding was used in the model since this antenna does not require a sophisticated feed structure as was needed in [13] to suppress the fundamental mode.

A converged representation of a single HWLW element was found by increasing the lateral sample rate. That antenna model was used to compare the diving-point impedance of a single terminated element with a

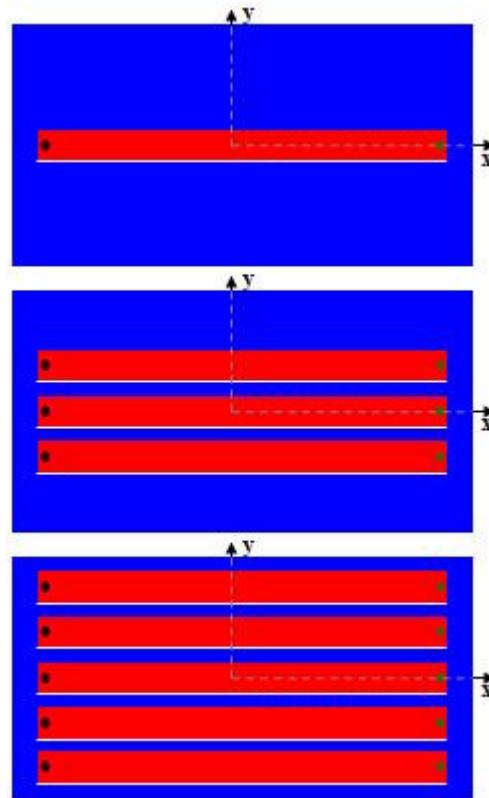


Figure 3. Three linear array geometries.

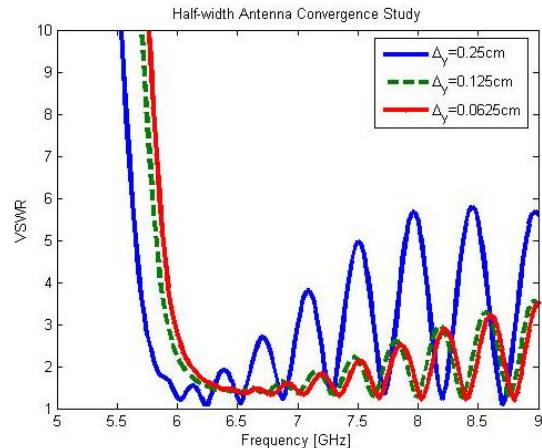


Figure 4. VSWR convergence study.

small array of terminated HWLW antennas. Fairly significant differences existed in the driving-point impedance implies a fairly strong mutual impedance between elements; presumably attributed to the leaky-waves excited in each antenna element. Hence, there is a clear need to compensate for mutual coupling in the design of such arrays and that pattern multiplication array beam synthesis will in general not be sufficient. Further results will be presented at the meeting.

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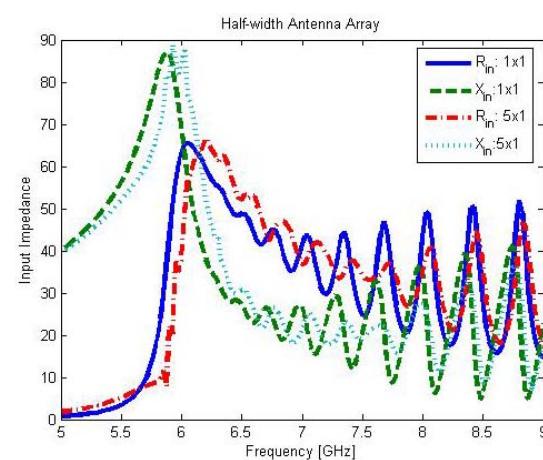


Figure 5. Comparison of the driving-point impedance for the center element of a 1x1 and a 5x5 array.